

Stacks in \LaTeX

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Abstract

There are several situations where we need to “forward reference” something that it is not yet available. For example, when we say something like “as we will see in chapter . . .” and when we make a bibliographic citation. Those situations are well treated in \LaTeX by the use of auxiliary files.

A different situation arises if we want to have a \LaTeX environment where one or more commands depend on the arguments given to other commands; that is, the values of the arguments of one command are taken from the arguments of another. We can also use an auxiliary file as a way of communication between commands but that implies that we have to process the document twice (at least) in order to complete the environment.

In this paper we describe an implementation of stacks in \TeX as a way to solve the problem just described. One command puts the information in the stack, the other command takes the information from the stack, and with this approach we manage to establish communication between commands while processing the document only once.

1 Introduction

In 1990 I was a PhD student in Computer Science and felt the need of a \LaTeX style file for producing diagrams, namely those used in Category Theory [4], e.g.

$$A \xrightarrow{f} B$$

So, I created a style file whose first version used the \LaTeX picture environment as the graphical engine, and in a later version switched to \PictEX because of its better capabilities. Since the first version the two main goals of the DCpic [5] package were:

- to have a \TeX -only format, in order to have good portability properties;
- to have a simple notation, a notation close to the graph notation where we describe a graph as a set of nodes (objects), and a set of arrows (morphisms) with each arrow having an initial and an end node.

So DCpic implements an environment $\text{\begin{dc} . . . \end{dc}}$, with the command $\text{\obj}(x,y)\{text\}$ for the nodes, and the command $\text{\mor}(x1,y1)(x2,y2)\{text\}$ for the arrows. The diagram pictured above has the following specification:

```
\begin{dc}
\obj(1,1){A}
```

```
\obj(3,1){B}
\mor(1,1)(3,1){f}
\end{dc}
```

The syntax is one of the simplest, if not the simplest, among packages of this type [2], but it deviates from the graph notation because the arrows specification is done in absolute terms and not in relative terms, i.e., it does not state the initial and end node of each arrow, but rather their positions. Since version 2 we began to look for a specification syntax that would allow the following specification for the diagram:

```
\begin{dc}
\obj(1,1){A}
\obj(3,1){B}
\mor{A}{B}{f}
\end{dc}
```

But this implies that the coordinates of objects A and B must be passed to the \mor command. We also want to pass the dimensions of the (box) objects to be able to adjust the arrow length accordingly.

How to do this? I saw two possible solutions:

- the \obj command writes all the information about its object in an auxiliary file, after which \mor reads the information from that file.
- the \obj command writes all the information about its object in an auxiliary structure kept in memory, after which \mor reads the information from that structure.

The first solution seemed to me too complicated to the problem at hand; it is also inefficient because for a large diagram we have to open and close the auxiliary file too many times (or enforce a strict separation between objects and morphisms). Because of this we chose the second approach and decided to implement stacks.

Using stacks the solution is very simple: \obj pushes the information onto the stack, and \mor looks for it on the stack and whenever necessary pops it from the stack.

2 Stacks

To implement stacks we need a structure in which to place the elements and functions to operate on the stack. Using the *Maude* [1, 3] syntax we have:

```
fmod STACK is
  sorts Elem NeStack Stack .
  subsorts Elem < NeStack < Stack .
  op empty : -> Stack .
  op push : Elem Stack -> NeStack .
  op pop : NeStack -> Stack .
  op top : NeStack -> Elem .
  op isempty : Stack -> Bool .
  var S : Stack .
```

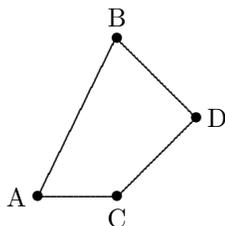


```

\begin{dc}\undigraph}[15]
\obj(1,1){A}[\west]
\obj(3,5){B}
\obj(3,1){C}[\south]
\obj(5,3){D}[\east]
\mor{A}{B}{}
\mor{A}{C}{}
\mor{B}{D}{}
\mor{C}{D}{}
\end{dc}

```

gives



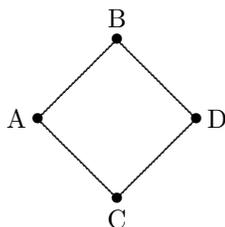
But, if we realize that we misplaced “A” we can correct that modifying the “A” coordinates only:

```

\begin{dc}\undigraph}[15]
\obj(1,3){A}[\west]
... the rest remains the same ...
\end{dc}

```

gives



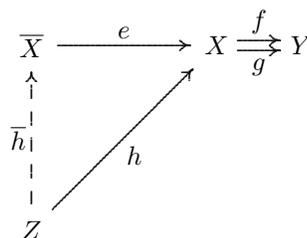
We can put almost anything in the stack, for example:

```

\begin{dc}\commdiag}[2]
\obj(1,1){X}
\obj(1,36){\overline{X}}
\obj(36,36){X}
\obj(52,36){Y}
\mor{X}{\overline{X}}{\overline{h}}%
[\atleft,\dasharrow]
\mor{X}{X}{h}[\atright,\solidarrow]
\mor{\overline{X}}{X}{e}
\mor(36,37)(52,37)[8,8]{f}
\mor(36,35)(52,35)[8,8]{g}[\atright,%
\solidarrow]
\end{dc}

```

gives



As you can see, the communication between `\obj` and `\mor` does not follow a strict first-in-last-out discipline; so what we do is to preserve the stack before a pop operation and recover the value afterwards. A list structure would be more appropriate for DCpic, but the simplicity of the stack implementation justifies, in our view, a little loss of efficiency.

3 Conclusions

Using an auxiliary structure like the stack gives us the possibility of organizing our \TeX programs with intercommunicating macros. The communication is established using the global variable `\stack`.

We decided not to deal with the error situations (e.g., a pop of the empty stack) in our implementation of stacks. The `\mor` command analyzes the stack to see whether it is empty; if so, then it writes an error message in the output and tries a naive error recovery using some default values.

The use of stacks in DCpic allows us to have a very simple notation for the graphs without a “visible” burden to the user. We are certain that this approach will be useful in other situations.

References

- [1] Manuel Clavel, Francisco Durán, Steven Eker, Lincoln Patrick, Narciso Martí-Oliet, Meseguer José, and Carolyn Talcott. *Maude Manual*. Computer Science Laboratory, SRI International, April 2005. Version 2.1.1.
- [2] Gabriel Valiente Feruglio. Typesetting commutative diagrams. *TUGboat*, 15(4):466–484, 1994.
- [3] Joseph Goguen and Timothy Winkler. Introducing OBJ. Technical Report SRI-CSL-88-9, SRI International, Computer Science Lab, August 1988.
- [4] Benjamin Pierce. *Basic Category Theory for Computer Scientists*. Foundations of Computing. The MIT Press, London, England, 1998.
- [5] Pedro Quaresma. DCpic, commutative diagrams in a (\LaTeX) document. In *Proceedings of the Euro \TeX 2001 conference*, Rolduc, The Netherlands, September 2001.